Algorithmic Aspects of Topology Control Problems for Ad hoc Networks

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Topology Control

- Assign powers to the nodes of an ad hoc network so as to induce a graph with appropriate properties (e.g. induced graph is connected).
- Battery power is a precious resource.
- Two objectives: Minimizing maximum power and minimizing total power.

Power Threshold Values

- Power threshold p(x, y): Minimum transmission power to be assigned to x so that a signal from x can reach y.
- Assumed to be *symmetric*; i.e., for all nodes x and y, p(x, y) = p(y, x).

Graph from Power Assignment

- Model used in [Ramanathan & Rosales-Hain, 2000].
- First, construct the directed graph (using the radio propagation model): Add directed edge (x, y) if the power assigned to x is at least p(x, y).
- For each pair of nodes u and v, if both (u, v) and (v, u) are present, then replace them by the undirected edge $\{u, v\}$.
- Delete all of the remaining directed edges.
- Two way communication model.
- The directed graph model can also be used.

Problem Formulation and Notation

- A topology control problem is specified by a triple ⟨M, P, O⟩.
 - $-\mathbb{M} \in \{\text{DIR}, \text{UNDIR}\}$ represents the graph model.
 - $-\mathbb{P}$ represents the desired graph property.
 - $-\mathbb{O} \in \{MAXP, TOTP\}$ represents the minimization objective (Max Power or Total Power).

Example: $\langle UNDIR, 1-NC, MAXP \rangle$

Interpretation: Assign powers so that resulting undirected graph is connected and the maximum power assigned to nodes is minimized.

Summary of Previous Work

- Minimizing Max Power [Ramanathan & Rosales-Hain, 2000]
 - Model for topology control problems.
 - Algorithms for $\langle UNDIR, 1-NC, MAXP \rangle$ and $\langle UNDIR, 2-NC, MAXP \rangle$.
 - Heuristics for distributed versions.
- Minimizing Total Power
 - NP-completeness of $\langle UNDIR, 1-NC, TOTP \rangle$ [Chen & Huang, 1989].
 - NP-completeness of (UNDIR, 1-NC, TOTP) for points in 2D space [Clementi et al, 1997].
 - 2-approximation for (UNDIR, 1-NC, TOTP)
 [Chen & Huang, 1989, Kirousis et al, 1997].

Main Contributions

- A general approach leading to a polynomial algorithm for minimizing maximum power for **monotone** graph properties.
- NP-completeness results showing the necessity of monotone properties.
- A general approach leading to an approximation algorithm for minimizing the total power for some monotone properties.
 - A new approximation algorithm for the problem of minimizing the total power for inducing a 2-node-connected graph.
- Empirical results showing the performance of the algorithm.

Monotone Graph Property

- Property unaffected by the addition of edges to the induced graph.
- Allows us to increase powers of nodes without affecting the property.

Examples:

- Monotone:
 - Connectedness.
 - Diameter $\leq k$.
- Not monotone:
 - Acyclicity.
 - Max node degree $\leq d$.

Algorithm for Minimizing Maximum Power

Main Ideas:

- There is an optimal solution in which each node is assigned the same power. (<u>Reason</u>: Monotonicity of ℙ.)
- 2. For a system with n nodes, the number of candidate solution values is $O(n^2)$.
- 3. Binary search over the candidate solution values $-O(\log n)$ calls to the algorithm for testing property \mathbb{P} suffice.

Other Results for Minimizing MAXP

- If ℙ is not monotone, then minimizing maximum power is NP-complete.
- Minimizing the number of nodes with maximum power is NP-complete even for monotone properties.

General Heuristic for Total Power

Assumptions: Property \mathbb{P} monotone and efficiently testable; power thresholds are symmetric.

Outline:

- 1. Construct complete graph $G_c(V, E_c)$, where each edge $\{x, y\}$ has weight w(x, y) = p(x, y) (power threshold).
- 2. Construct an edge subgraph G'(V, E') of G_c so that G' satisfies \mathbb{P} and the total weight of edges in E' is minimum or near-minimum.
- 3. For each node x, power(x) is given by

 $Max\{w(x,y) : \{x,y\} \text{ is an edge in } G'\}.$

Note: Step 2 depends on \mathbb{P} .

Examples from the General Outline

- **Ex 1:** Approximating $\langle \text{UNDIR}, 1\text{-}\text{NC}, \text{TOTP} \rangle$
 - In Step 2, construct a minimum spanning tree for G_c [Kirousis et al, 1997].

Ex 2: Approximating $\langle \text{UNDIR}, 2\text{-NC}, \text{TOTP} \rangle$:

 In Step 2, use the heuristic for minimum weight 2-NC subgraph from [Khuller & Raghavachari,1996].

Experimental Results

- Results are for $\langle UNDIR, 2-NC, TOTP \rangle$.
- Experimental setup similar to that discussed in [Ramanathan & Rosales-Hain, 2000].
- Comparison with the results for $\langle UNDIR, 2\text{-}NC, MAXP \rangle$ from [RR, 2000].
- Both uniform node density and skewed node density were considered.

Uniform Node Density



Power vs Node Density

- Average power less than that of [RR, 2000] by 5% to 15%.
- Maximum power is 14% to 31% larger.

Uniform Node Density (continued)



Degree vs Node density

• Average node degree consistently smaller than [RR, 2000].

Skewed Node Density



Power vs Node density

- Average power less than that of [RR, 2000] by 6% to 14%.
- Maximum power is 12% to 20% larger.

Skewed Node Density (continued)



Degree vs Node density

• Average node degree consistently smaller.

Additional Recent Results

- Approximation algorithm for minimizing total power for inducing a network of small diameter.
- An O(log n) approximation algorithm for minimizing the total power for inducing a connected network under asymmetric power threshold values.