

403: Algorithms and Data Structures

Lower Bound for Sorting & The closest pair in 2D

Fall 2016

UAlbany

Computer Science

So far: Sorting

<i>Algorithm</i>	<i>Time</i>	<i>Space</i>
• Insertion	$O(n^2)$	in-place
• Merge	$O(n \log n)$	2 nd array to merge
• Heapsort	$O(n \log n)$	in-place
• Quicksort	from $O(n \log n)$ to $O(n^2)$	in-place

Can we do better than $O(n \log n)$?

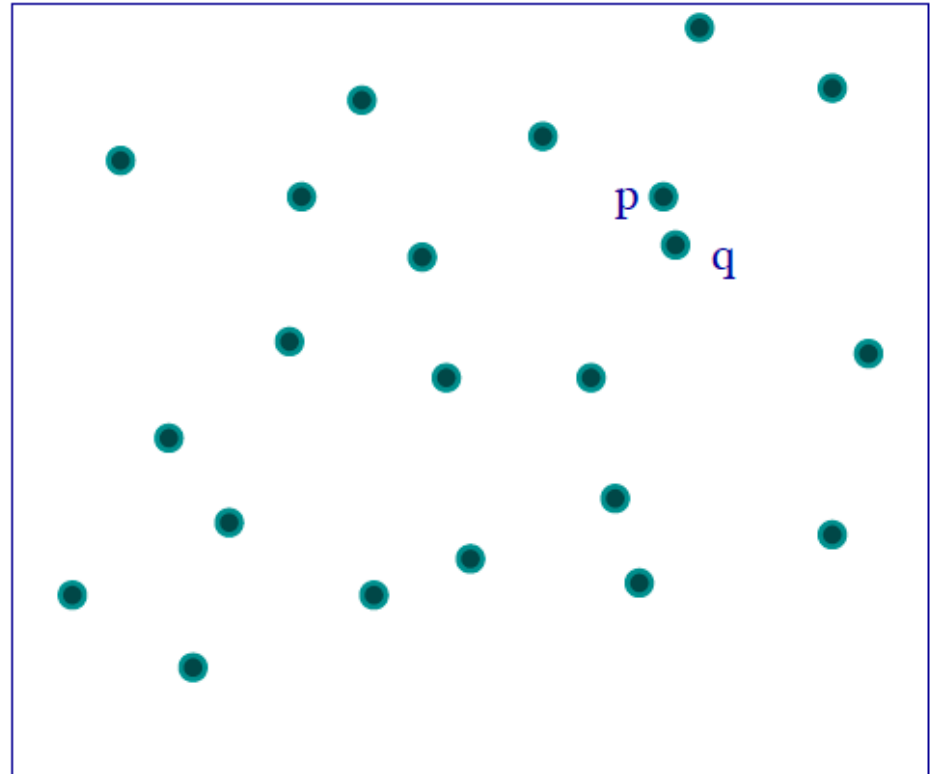
Spoiler: Not if we do comparisons only

Lower bound on comparison sorts

- Any algorithm performing only comparisons runs in $n \log n$)
- We will prove this using the concept of **decision trees**

Closest pair in 2D

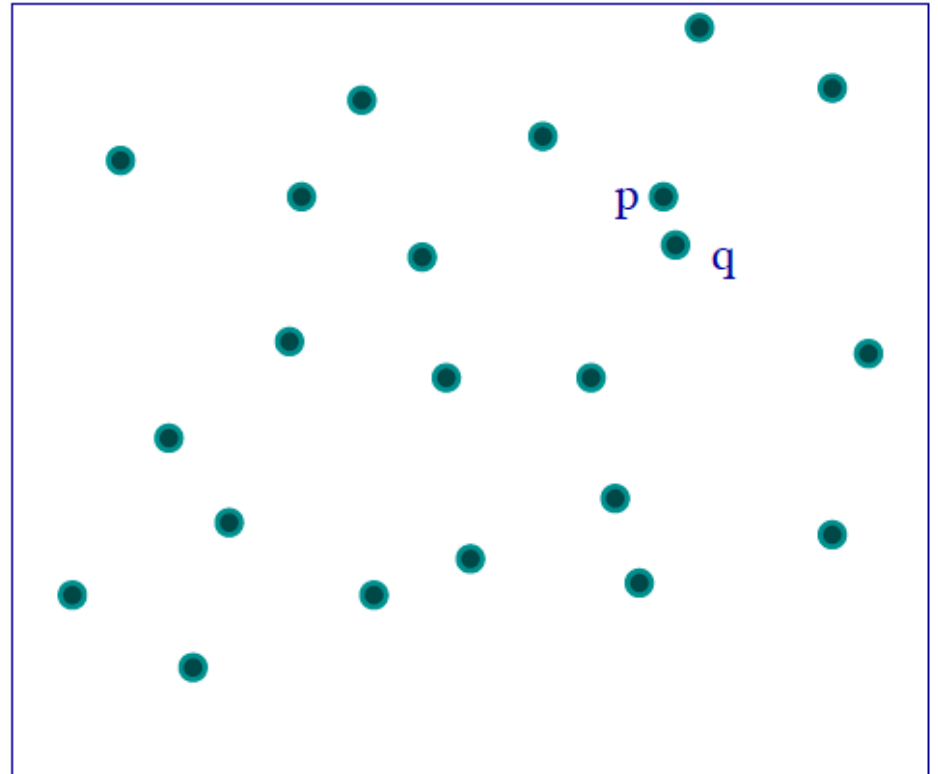
- Given n points in 2-dimensions, find two whose mutual distance is smallest.
- Euclidean distance



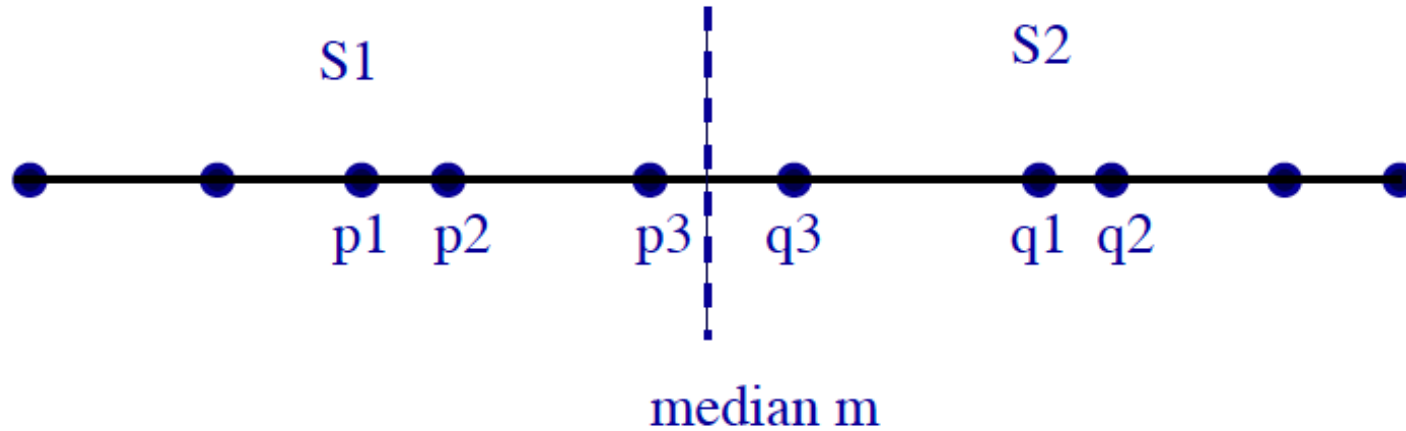
$$d(p, q) = \sqrt{(x_p - x_q)^2 + (y_p - y_q)^2}$$

Closest pair in 2D

- Brute force?
 - Consider all pairs
- Complexity?
 - $O(n^2)$

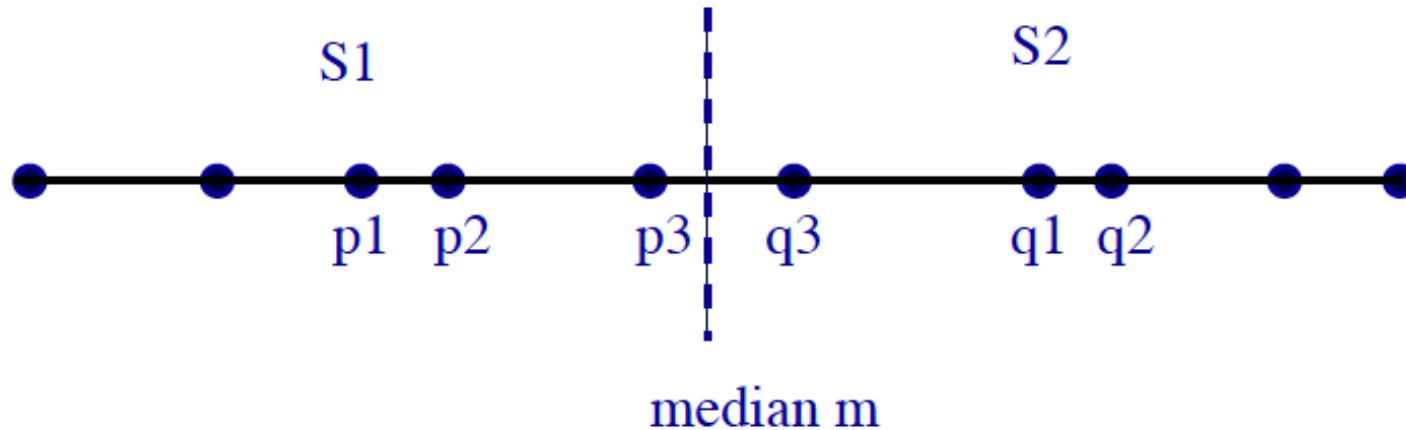


Divide-And-Conquer (1D)



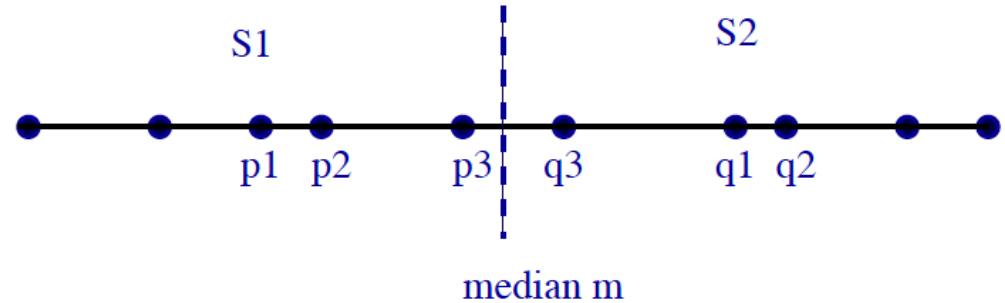
- We can simply sort and consider consecutive pairs $O(n \log n)$
 - Does not generalize to 2D

Divide-And-Conquer (1D)



- DIVIDE: split array in two equal parts
- CONQUER: recursively find closest pair in parts
- COMBINE:
 - Let d be the smallest separation in $S1$ and $S2$
 - If $\text{dist}(p3, q3) < d$ return $\text{dist}(p3, q3)$ else d

Divide-And-Conquer (1D) Pseudo code



Closest-Pair-1D(S)

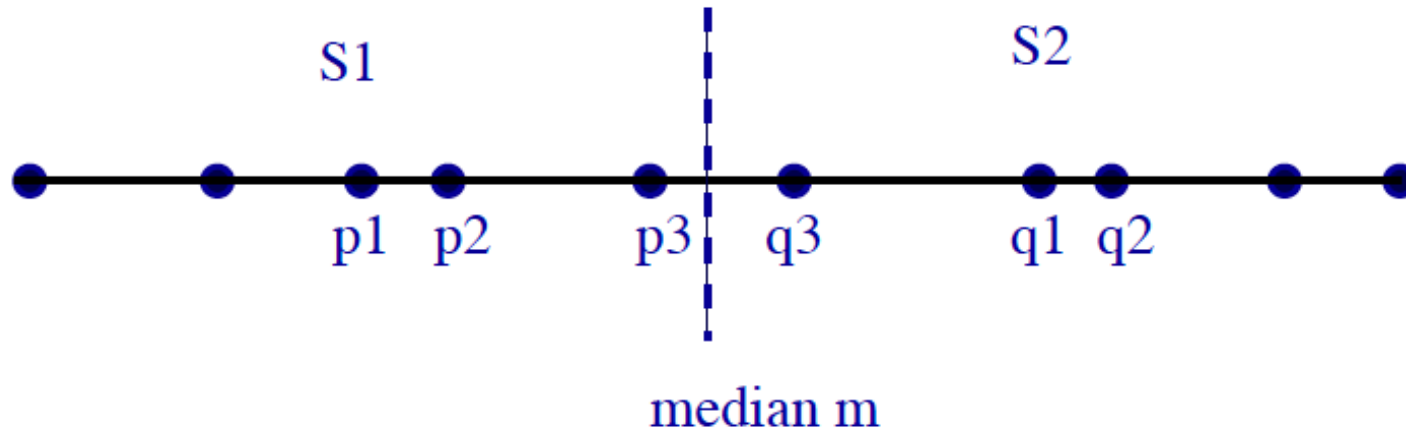
If $|S| = 1$, output $d = \text{infinity}$

If $|S| = 2$, output $d = |p_2 - p_1|$

Otherwise, do the following steps:

1. Let $m = \text{median}(S)$
2. Divide S into S_1, S_2 at m .
3. $d_1 = \text{Closest-Pair-1D}(S_1)$.
4. $d_2 = \text{Closest-Pair-1D}(S_2)$.
5. d_{12} is minimum distance across the cut.
6. Return $d = \min(d_1; d_2; d_{12})$

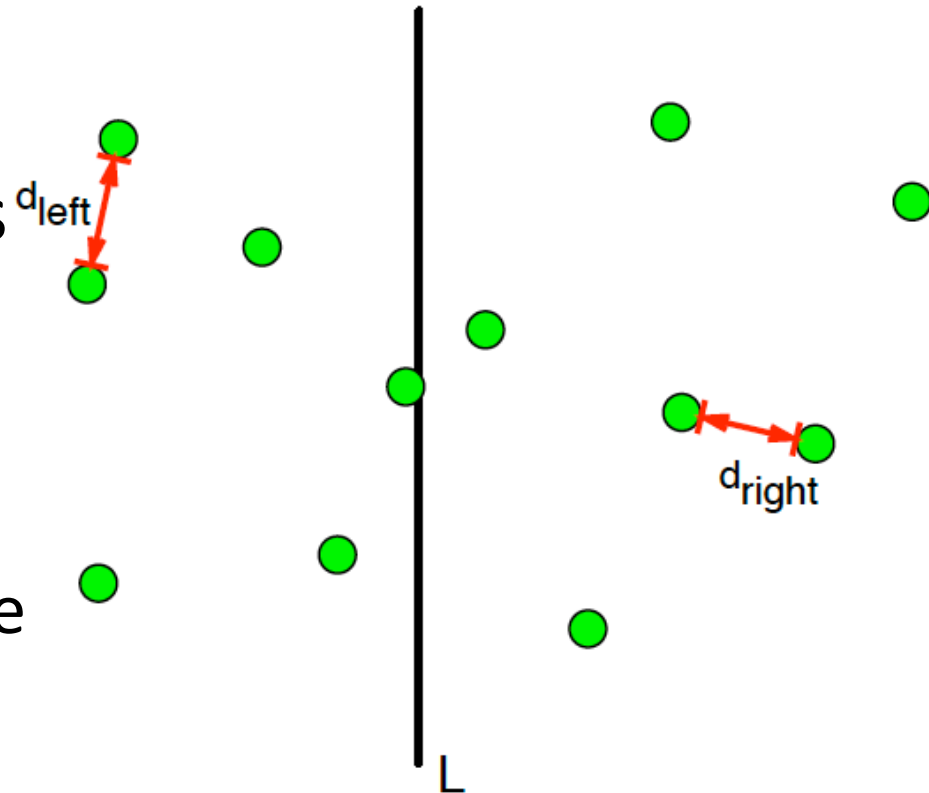
Divide-And-Conquer (1D)



- Key observation: If m is the dividing coordinate, then $p3$, $q3$ must be within d of m .
 - $p3$ must be the rightmost point in $S1$
 - $q3$ must be the leftmost point in $S2$
 - Hard to generalize to 2D
- How many points of $S1$ can be in $(m-d, m]$?

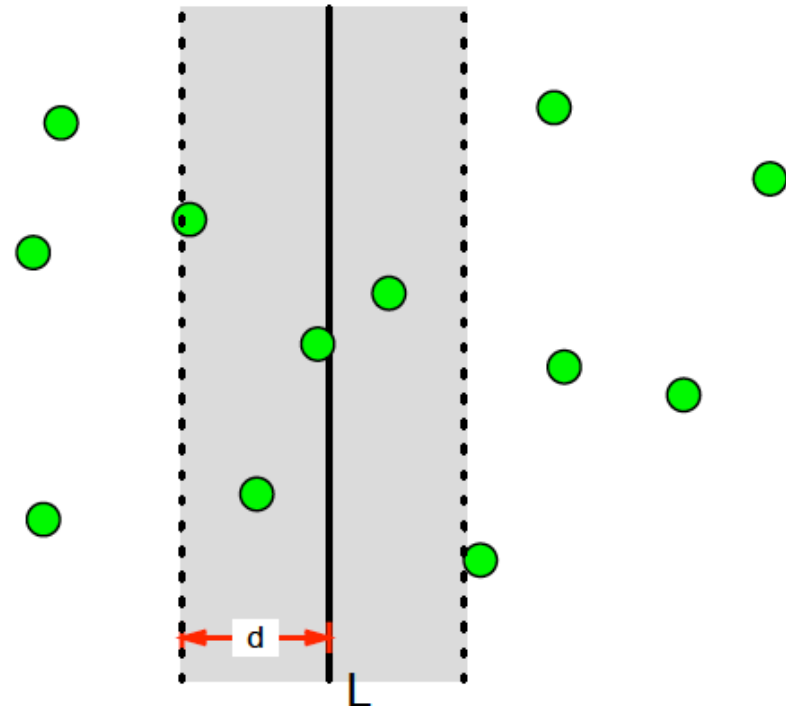
Divide-And-Conquer (2D)

- DIVIDE: split points in two equal parts with line L
- CONQUER: recursively find closest pair in parts d_{left}
- COMBINE:
 - $d = \min(d_{\text{left}}, d_{\text{right}})$
 - d is the answer unless L split points that are close



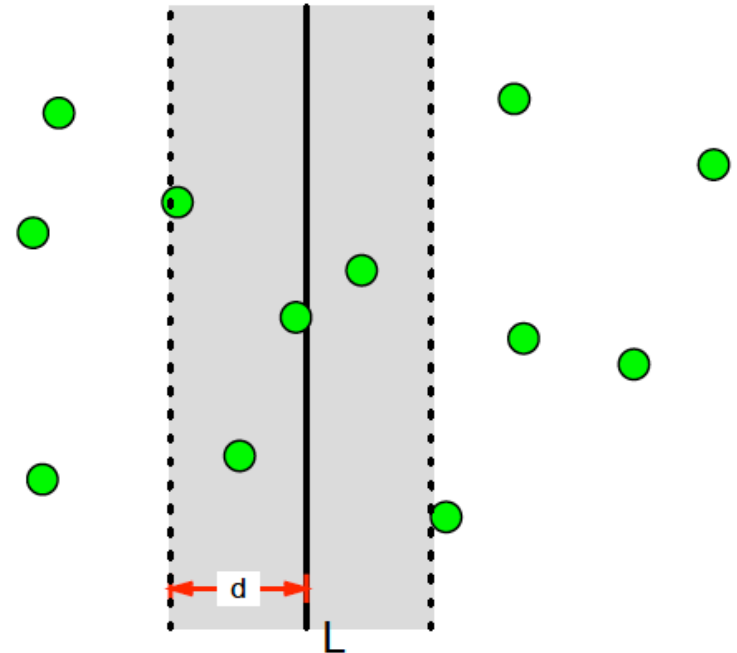
Region near L

- If there is a pair (p,q) within distance d split by L , then both p and q must be within d from L
- Let S_y be an array of points in the region sorted by y coordinate
- size of S_y might be $O(|S|)$
 - Cannot check all pairs

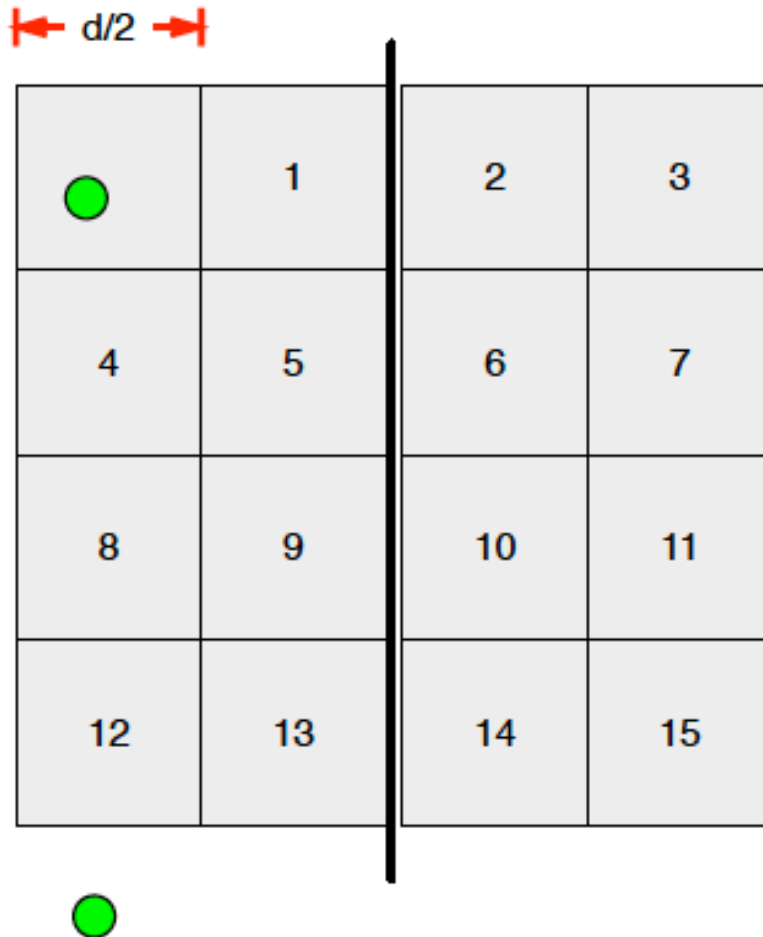


Special structure in S_y

- Let: $S_y = p_1, p_2 \dots p_m$, then if $\text{dist}(p_i, p_j) < d$ then $j - i \leq 15$
- close-by points are closeby in the array

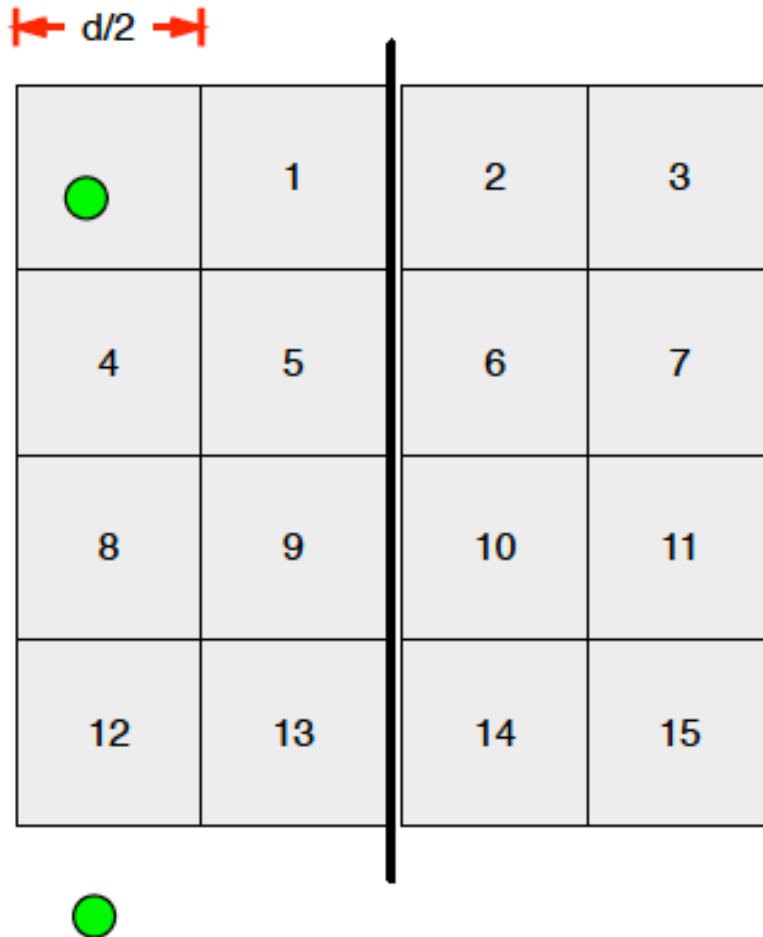


Proof: close points within 15 positions



- Divide the region in squares of side $d/2$
- How many points in each box?
- At most 1
 - Each box is contained in one half
 - No 2 points in a half are closer than d

Proof: close points within 15 positions



- Suppose 2 points separated by 15 indices
- At least 3 full rows separate them
- Height of 3 rows $> 3d/2 > d$
- Points are farther than d from each other

Divide and Conquer(2D)

ClosestPair(ptsX, ptsY)

1. if (`size(ptsX)<2`) return `null`
2. if (`size(ptsX)==2`) return `ptsX`
3. `m`=median of x coordinates
4. Prepare subsets to the left of `m`: `ptsX-left`, `ptsY-left` and to the right of `m`: `ptsX-right`, `ptsY-right` // They should be sorted but you should not use sorting (see book chapter)

DIVIDE

5. `pair-left` = `ClosestPair(ptsX-left, ptsY-left)`
6. `pair-right` = `ClosestPair(ptsX-right, ptsY-right)`

CONQUER

7. `d` = min of distances between `pair-left` and `pair-right`
8. `res` = pair among `pair-left` and `pair-right` of the smaller distance
9. `ptsWithinD`: an array of points within distance `d` from `m`, sorted by y coordinates
10. for `i=1...ptsWithinD.length`
11. for `j=i+1...min(ptsWithinD.length,i+15)`
12. if `dist(ptsWithinD[i], ptsWithinD[j])<d`
13. `res` = (`ptsWithinD[i]`, `ptsWithinD[j]`)
14. `b` = `dist(ptsWithinD[i], ptsWithinD[j])`
15. return `res`

COMBINE: $O(n)$

Analysis

- Divide set of points in half each time:
 - depth of recursion is $O(\log n)$
- Merge takes $O(n)$ time.
- Recurrence: $T(n) = 2T(n/2) + cn$
- Same as MergeSort: $O(n \log n)$ time.